**Project Timeline**

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| Date | Milestone |
| SAT 6/4 | * Car design * Control the stepper via controller (the robot can walk) |
| SAT 13/4 | * Wireless controlling (parallel interfacing) * Finish the car design (servo stand) * Integrate all other robot component (servo - ultrasonic) |
| SAT 20/4 | * The PC interfacing program * Initialize the 2 modes of operation for the robot |
| SAT 27/4 | Final testing  And  Ready to deliver |
| SAT 4/5 | Delivery |